Vector[™] H320[™] GNSS Compass Module

Advanced Heading & RTK Positioning

- Extremely accurate heading with short baselines
- L1/L2 GPS/GLONASS RTK capable
- L-Band DGNSS/HP/XP (OmniSTAR®) capable
- Excellent coasting performance
- Fast RTK acquisition and reacquisition times
- 5 cm rms RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection



Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vector $^{\mathbb{M}}$ H320 $^{\mathbb{M}}$ is our most advanced GNSS heading and positioning module available from Hemisphere GNSS.

The Vector H320 utilizes dual antenna ports to create a series of additional capabilities to Eclipse™ Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard L-Band DGNSS/HP/XP reception, RTK-enabled heave, low power consumption, and precise timing.

Integrate the Vector H320 into your applications to experience exceptional performance, flexibility and cost savings. This incredible GNSS module uses advanced multipath mitigation techniques and offers full scalability and expandability from L1/L2 GPS/GLONASS to L1/L2 GPS/GLONASS RTK performance.



GPS Sensor Specifications

ReceiverType: **Dual GNSS RTK**

Signals Received: GPS, GLONASS, and GALILEO7

Channels: 270 **GPS Sensitivity:** -142 dBm

SBAS Tracking: 3-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional Horizontal Accuracy: RMS (67%) 2DRMS (95%) RTK: 1 10 mm + 1 ppm 20 mm + 2 ppm

L-band DGNSS/HP/XP (OmniSTAR): 2,8 0.08 m SBAS (WAAS): 2 0.25 m

 $0.50 \, \text{m}$ Autonomous, no SA: 2 2.50 m 1.20 m < 0.17° rms @ 0.5 m antenna separation Heading Accuracy: < 0.09° rms @ 1.0 m antenna separation < 0.04° rms @ 2.0 m antenna separation

< 0.02° rms @ 5.0 m antenna separation Pitch / Roll Accuracy: < 1° rms

30 cm rms (DGPS)6, 5 cm rms (RTK)6 Heave Accuracy:

Timing (1PPS) Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: < 40 s typical (no almanac or RTC) Warm Start: < 20 s typical (almanac and RTC) Hot Start: < 5 s typical (almanac, RTC and position)

Heading Fix: < 10 s typical (Hot Start)

Antenna Input Impedance: 50 Ω

1,850 kph (999 kts) Maximum Speed: 18,288 m (60,000 ft) Maximum Altitude:

L-band DGNSS/HP/XP Sensor Specifications

-130 dBm Sensitivity: Channel Spacing: 7.5 kHz

Satellite Selection: Manual and Automatic Reacquisition Time: 15 seconds (typical) Rejection: 15 kHz spacing > 30 dB, 300 kHz spacing > 60 dB

DSP for demodulation and protocol Processor:

decoding module provides processing for

the differential algorithms

Command Support: Reports L-band DGNSS/HP/XP (OmniSTAR)

region, satellite info, allows input and status of L-band DGNSS/HP/XP (OmniSTAR

subscription, Bit Error Rate output for reception quality indication and manual frequency tuning

Communications

Serial Ports: 4 full-duplex 3.3 V CMOS (3 main serial ports, 1 differential-only port), 1 USB Host, 1 USB Device

4800 - 115200

Baud Rates:

Correction I/O Protocol: RTCM SC-104, L-Dif™, RTCM v2.3 (DGPS), RTCM v3 (RTK), CMR, CMR+

Data I/O Protocol: NMEA 0183, Crescent binary 3, L-Dif Timing Output: 1PPS, CMOS, active low, falling edge sync,

10 k Ω , 10 pF load **Event Marker Input:**

CMOS, active low, falling edge sync, 10 k Ω ,

10 pF load Pin 62

Heading Warning I/O:

Power

Input Voltage: Power Consumption: **Current Consumption:** Power Consumption:

Current Consumption: L-band Antenna Voltage:

Antenna Short Circuit Protection:

Antenna Gain Input Range: 10 to 40 dB Antenna Input Impedance: 50 Ω

Environmental

Operating Temperature: Storage Temperature:

Humidity:

Mechanical

Dimensions: Weight:

Status Indication (LED):

Power/Data Connector: **Antenna Connectors**

Aiding Devices

Tilt Sensors:

3.3 VDC +/- 5%

< 3.2 W at 3.3 V (L1/L2 GPS/GLONASS)

< 970 mA at 3.3 V (L1/L2 GPS/GLONASS)

< 3.9W at 3.3V (L1/L2 GPS/GLONASS; L-band

DGNSS/HP/XP)

< 1180 mA at 3.3V (L1/L2 GPS/GLONASS;

DGNSS/HP/XP) 15 VDC maximum

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F)

95% non-condensing (when installed in an

enclosure)

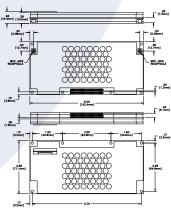
15.2 L x 7.1 W x 1.6 H (cm) 6.0 L x 2.8 W x 0.63 H (in) .105 kg (3.70 oz.)

Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-band DGNSS/HP/XP lock 70-pin male header, 0.05" pitch (1.27 mm)

MCX, female, straight

Provides smooth heading, fast heading reacquisition and reliable < 0.5° per min heading for periods up to 3 min. when loss of GPS has occurred 4

Provide pitch, roll data and assist in fast start-up and reacquisition of heading solution





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Depends on multipath environment, antenna selection, number of satellites in view, satellite geometry, baseline length (for local services), and ionospheric activity

2 Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

³ Hemisphere GPS proprietary

4 Under static conditions

This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation

6 Based on a 40 second time constant

7 Upgrade required

Authorized Distributor:



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