Vector™ VS131™ GNSS Compass

Professional Heading and Positioning GNSS Compass

- Enhanced heading performance with GLONASS
- GNSS heading better than 0.04° RMS
- L1 GPS/GLONASS RTK capable
- Additional satellite tracking ensures a robust solution
- Maintains heading and position lock in obstructed areas
- Accurate heading up to 3 minutes during GPS outages
- COAST™ technology maintains differentially-corrected positioning for 40 minutes or more after loss of differential signal
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites



Enhanced GNSS heading and positioning technology with GLONASS. Precise marine and land applications demand the heading and positioning performance of the Vector™ VS131™ receiver making it ideal for professional machine control and navigation applications in any environment.

The Vector VS131 utilizes all of the innovations of Hemisphere GNSS' Crescent® Vector technology, offering a series of features to the Vector VS131 including heave, pitch, and roll output.

The Vector VS131 receiver, with its display and user interface, can be conveniently installed near the operator. The two antennas are mounted separately and with a user-determined separation to meet the desired accuracy. The Vector VS131 is L-Band DGNSS (VBS), Beacon, and SBAS capable for differential GNSS positioning. Our MFA DGNSS patented technology allows the VS131 to smoothly transition between DGNSS systems.





GNSS Sensor Specifications

Receiver Type: Vector GNSS L1 RTK Receiver

Signals Received: GPS, GLONASS

Channels: 540 GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking Update Rate: 10 Hz standard, 20 Hz optional

Positioning Accuracy

Horizontal Vertical Single Point, no SA 1: 2.5 m 1.2 m SBAS (WAAS) 2: $0.3 \, m$ 0.6 m L-Band DGNSS 3: 0.6 m $0.3 \, m$

Code Differential

GNSS 1: 0.3 m 0.6 m

RTK 2, 4: 10 mm + 1 ppm 20 mm + 2 ppm Heading Accuracy: 0.30° rms @ 0.5 m antenna separation

0.15° rms @ 1.0 m antenna separation 0.08° rms @ 2.0 m antenna separation 0.04° rms @ 5.0 m antenna separation

Pitch/Roll Accuracy

(RMS):

Heave Accuracy (RMS): 30 cm5 Timing (1PPS) Accuracy: 20 ns

Rate of Turn: 90°/s maximum

Cold Start: 60 s (no almanac or RTC) Warm Start: 20 s typical (almanac and RTC) Hot Start: 1 s typical (almanac, RTC and position)

Heading Fix: 10 s typical (valid position) 1,850 mph (999 kts) Maximum Speed: Maximum Altitude: 18,288 m (60,000 ft)

Differential Options: SBAS, Beacon, External RTCM, L-Band (VBS/HP/

XP/G2) and RTK

Beacon Sensor Specifications

Channels: 2-channel parallel tracking Frequency Range: 283.5 to 325.0 kHz

Manual, Automatic, and Database Operating Modes: Compliance: IEC 61108-4 beacon standard

L-Band Sensor Specifications

Sensitivity: -130 dBm Channel Spacing: 7.5 kHz

Manual and Automatic Satellite Selection: Reacquisition Time: 15 seconds (typical) Rejection: 15 kHz spacing > 30 dB, 300 kHz spacing > 60 dB

Communication

Serial Ports: 2 full-duplex RS232 ports

USB Ports: 1 USB-B Baud Rates: 4800 - 115200

Correction I/O Protocol: RTCM SC-104, L-Dif™ 6, RTCM v2 (DGPS), RTCM v3 (RTK), CMR (RTK), CMR+ (RTK)

Data I/O Protocol: NMEA 0183, Hemisphere GNSS binary ⁶ 1 PPS (CMOS, active high, rising edge sync, 10 Timing Output:

 $k\Omega$, 10 pF load)

Power

Input Voltage: 8 to 36 VDC

4.5 W nominal (GPS L1 + GLONASS L1) Power Consumption:

4.8 W nominal (GPS L1 + GLONASS L1 + Beacon) 5.5 W nominal (GPS L1 + GLONASS L1 + L-Band)

Current Consumption: 0.34 A nominal (GPS L1 + GLONASS L1) 0.40 A nominal (GPS L1 + GLONASS L1 + Beacon)

5 VDC maximum 60 mA

0.46 A nominal (GPS L1 + GLONASS L1 + L-Band)

Power Isolation: Reverse Polarity Protection:

Antenna Voltage:

Antenna Short Circuit Protection:

Yes Antenna Gain Input Range:

10 to 40 dB Antenna Input Impedance: 50 Ω

Environmental

-30°C to + 70°C (-22°F to + 158°F) Operating Temperature: Storage Temperature: -40°C to + 85°C (-40°F to + 185°F)

Humidity: 95% non-condensing Mechanical Shock: EP455 Section 5.14.1

Vibration: EP455 Section 5.15.1 Random

CE (IEC 60945 Emissions and Immunity) EMC:

FCC Part 15, Subpart B

IP66 (IEC 60529) Enclosure:

Mechanical

20.2 L x 12.0 W x 7.5 H (cm) Dimensions: 8.0 L x 4.7 W x 3.0 H (in)

Status Indications (LED): Power, Primary and Secondary GNSS lock,

Differential lock, DGNSS position, Heading, L-Band

Power Switch: Front panel soft switch **Power Connector:** 2-pin ODU metal circular

Data Connector: DB9 (sealed) Antenna Connectors: 2TNC (female)

Aiding Devices

Tilt Sensors:

Provides heading smoothing with GNSS. Drift rate Gyro:

is 1° per minute in heading for periods up to 3 minute when loss of GNSS has occurred 4 Provide pitch, roll data, assist in fast start-up

and heading reacquisition.

- 1 Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity
- 2 Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry
- 3 Requires a subscription from OmniSTAR®
- 4 Depends on multipath environment, number of satellites in view, satellite geometry, baseline length (for differential services), and ionospheric activity
- 5 Based on a 40 second time constant
- 6 Hemisphere GNSS proprietary

Authorized Distributor:

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